

# Package: h3o (via r-universe)

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**Title** H3 Geospatial Indexing System

**Version** 0.2.2

**Description** A dependency free interface to the H3 geospatial indexing system utilizing the Rust library 'h3o'  
<https://github.com/HydroniumLabs/h3o> via the 'extandr' library <https://github.com/extandr/extandr>.

**License** MIT + file LICENSE

**Encoding** UTF-8

**Language** en

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**SystemRequirements** Cargo (rustc package manager)

**Imports** rlang, stats, vctrs

**Suggests** sf, wk

**Config/rextandr/version** 0.3.1.9000

**Repository** https://josiahparry.r-universe.dev

**RemoteUrl** https://github.com/josiahparry/h3o

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## Contents

compact_cells . . . . .	2
get_parents . . . . .	2
grid_disk . . . . .	3
h3_edges . . . . .	5
h3_from_xy . . . . .	6
h3_resolution . . . . .	8
is_nb_pairwise . . . . .	9
sfc_to_cells . . . . .	9

## Index

11

compact\_cells

*Compact H3 Cells***Description**

Reduce a set of H3 indices of the same resolution to the minimum number of H3 indices of varying resolution that entirely covers the input area.

**Usage**

```
compact_cells(x)
uncompact_cells(x, resolution)
```

**Arguments**

x	a vector of H3 indexes.
resolution	a scalar integer representing the grid resolution in the range [0, 15].

**Examples**

```
x <- h3_from_strings("841f91dfffffff")
y <- uncompact_cells(x, 5)[[1]]
z <- compact_cells(y)
all.equal(x, z)
```

get\_parents

*Hierarchical H3 Grid Functions***Description**

Functions used to traverse the hierarchy of H3 grids.

**Usage**

```
get_parents(x, resolution)
get_children(x, resolution)
get_children_count(x, resolution)
get_children_center(x, resolution)
get_children_position(x, resolution)
get_children_at(x, position, resolution)
```

## Arguments

x	an H3 vector.
resolution	a scalar integer representing the grid resolution in the range [0, 15].
position	the integer position in the ordered set of cells.

## Details

- `get_parents()`: returns the parent cells for an H3 vector at a given resolution. Errors if the resolution is smaller than the provided cell.
- `get_children()`: returns a list of H3 vectors containing the children of each H3 cell at a specified resolution. If the resolution is greater than the cell's resolution an empty vector is returned.
- `get_children_count()`: returns an integer vector containing the number of children for each cell at the specified resolution.
- `get_children_center()`: returns the middle child (center child) for all children of an H3 cell at a specified resolution as an H3 vector.
- `get_children_position()`: returns the position of the observed H3 cell in an ordered list of all children as a child of a higher resolution cell (PR for clearer language welcome).
- `get_children_at()`: returns the child of each H3 cell at a specified resolution based on its position in an ordered list (PR for clearer language welcome).

## Examples

```
h3_strs <- c("841f91dfffffff", "841fb59fffffff")
h3 <- h3_from_strings(h3_strs)

get_parents(h3, 3)
get_children(h3, 5)
get_children_count(h3, 6)
get_children_position(h3, 3)
get_children_at(h3, 999, 10)
```

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## Description

Functions used to traverse the H3 grid.

## Usage

```
grid_disk(x, k = 1, safe = TRUE)

grid_ring(x, k = 1)
```

```
grid_distances(x, k = 1)

grid_path_cells(x, y)

grid_path_cells_size(x, y)

grid_distance(x, y)

grid_local_ij(x, y)
```

## Arguments

x	an H3 vector.
k	the order of ring neighbors. 0 is the focal location (the observed H3 index). 1 is the immediate neighbors of the H3 index. 2 is the neighbors of the 1st order neighbors and so on.
safe	default TRUE. If FALSE uses the fast algorithm which can fail.
y	an H3 vector.

## Details

- *grid\_disk()*: returns the disk of cells for the identified K ring. It is a disk because it returns all cells to create a complete geometry without any holes. See *grid\_ring()* if you do not want inclusive neighbors.
- *grid\_ring()*: returns a K ring of neighbors around the H3 cell.
- *grid\_distances()*: returns a list of numeric vectors indicating the network distances between neighbors in a K ring. The first element is always 0 as the travel distance to one's self is 0. If the H3 index is missing a 0 length vector will be returned.
- *grid\_path\_cells()*: returns a list of H3 vectors indicating the cells traversed to get from x to y. If either x or y are missing, an empty vector is returned.
- *grid\_path\_cells\_size()*: returns an integer vector with the cell path distance between pairwise elements of x and y. If either x or y are missing the result is NA. *grid\_distance()*: returns an integer vector with the network distance between pairwise elements of x and y. If either x or y are missing the result is NA. Effectively *grid\_path\_cells\_size()* - 1.
- *grid\_local\_ij()* returns a two column data frame containing the columns i and j which correspond to the i,j coordinate directions to the destination cell.

## Examples

```
h3_strs <- c("841f91dfffffff", "841fb59fffffff")
h3 <- h3_from_strings(h3_strs)

grid_disk(h3, 1)
grid_ring(h3, 2)
grid_distances(h3, 2)
grid_path_cells(h3, rev(h3))
grid_path_cells_size(h3, rev(h3))
```

```
grid_distance(h3, rev(h3))
grid_local_ij(h3, rev(h3))
```

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h3\_edges

*H3 Edges*

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## Description

Functions to create or work with H3Edge vectors. See Details for further details.

## Usage

```
h3_edges(x, flat = FALSE)

h3_shared_edge_sparse(x, y)

h3_shared_edge_pairwise(x, y)

is_edge(x)

is_valid_edge(x)

h3_edges_from_strings(x)

flatten_edges(x)

h3_edge_cells(x)

h3_edge_origin(x)

h3_edge_destination(x)

## S3 method for class 'H3Edge'
as.character(x, ...)
```

## Arguments

x	an H3 vector
flat	default FALSE. If TRUE return a single vector combining all edges of all H3 cells.
y	an H3 vector
...	unused.

## Details

- `h3_edges()`: returns a list of H3Edge vectors for each H3 index. When `flat = TRUE`, returns a single H3Edge vector.
- `h3_shared_edge_pairwise()`: returns an H3Edge vector of shared edges. If there is no shared edge NA is returned.
- `h3_shared_edge_sparse()`: returns a list of H3Edge vectors. Each element iterates through each element of `y` checking for a shared edge.
- `is_edge()`: returns TRUE if the element inherits the H3Edge class.
- `is_valid_edge()`: checks each element of a character vector to determine if it is a valid edge ID.
- `h3_edges_from_strings()`: create an H3Edge vector from a character vector.
- `flatten_edges()`: flattens a list of H3Edge vectors into a single H3Edge vector.
- `h3_edge_cells()`: returns a list of length 2 named H3Edge vectors of `origin` and `destination` cells
- `h3_edge_origin()`: returns a vector of H3Edge origin cells
- `h3_edge_destination()`: returns a vector of H3Edge destination cells

`h3_from_xy`

*Create H3 Index*

## Description

Create H3 indices from sfc objects, vectors of x and y coordinates, or H3 string IDs.

## Usage

```

h3_from_xy(x, y, resolution)

h3_from_points(x, resolution)

h3_from_strings(x)

h3_to_points(x)

h3_to_vertexes(x)

## S3 method for class 'H3'
as.character(x, ...)

flatten_h3(x)

is_h3(x)

```

## Arguments

- x for h3\_from\_points() an object of class sfc\_POINT. For h3\_from\_strings() a character vector of H3 index IDs. For h3\_from\_xy() a numeric vector of longitudes.
- y a numeric vector of latitudes.
- resolution an integer indicating the H3 cell resolution. Must be between 0 and 15 inclusive.
- ... unused.

## Details

- h3\_from\_points(): takes an sfc\_POINT object and creates a vector of H3 cells
- h3\_from\_strings(): converts a character vector of cell indexes to an H3 vector
- h3\_from\_xy(): converts vectors of x and y coordinates to an H3 vector
- h3\_to\_points(): converts an H3 vector to a either an sfc\_POINT object or a list of sfg POINT objects.
- h3\_to\_vertexes(): converts an H3 vector to an sfc\_MULTIPOINT object or a list of MULTIPROJECT objects.

## Examples

```

h3_from_xy(-90, 120, 5)

h3_from_strings("85f29383ffffffff")

if (requireNamespace("sf")) {
  # create random points
  pnts <- sf::st_cast(
    sf::st_sf(
      sf::st_multipoint(matrix(runif(10, max = 90), ncol = 2)),
      crs = 4326
    ),
    "POINT"
  )

  # convert to H3 objects
  h3s <- h3_from_points(pnts, 5)

  h3_to_vertexes(h3s)

  h3_to_points(h3s)
}

h3_ids <- c("831f91ffffffff", "831fb5ffffffff", "831f94ffffffff")

flatten_h3(
  list(
    NULL,
    h3_from_strings(h3_ids),
    h3_from_strings(h3_ids[1])
)

```

```
)  
)
```

---

**h3\_resolution**      *H3 Inspection Functions*

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## Description

Functions that provide metadata about H3 indexes.

## Usage

```
h3_resolution(x)  
h3_base_cell(x)  
is_valid_h3(x)  
is_res_class_iii(x)  
get_face_count(x)
```

## Arguments

**x**      an H3 vector.

## Details

- `h3_resolution()`: returns the resolution of each H3 cell.
- `h3_base_cell()`: returns the base cell integer.
- `is_valid_h3()`: given a vector of H3 index string IDs, determine if they are valid.
- `is_res_class_iii()`: determines if an H3 cell has Class III orientation.
- `is_pentagon()`: determines if an H3 cell is one of the rare few pentagons.
- `get_face_count()`: returns the number of faces that intersect with the H3 index.

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is_nb_pairwise	<i>H3 index neighbors</i>
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## Description

H3 index neighbors

## Usage

```
is_nb_pairwise(x, y)  
is_nb_sparse(x, y)
```

## Arguments

x	an H3 vector.
y	and H3 vector.

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sfc_to_cells	<i>Convert sf geometry to H3 Cells</i>
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## Description

Given a vector of sf geometries (class `sfc`) create a list of H3 vectors. Each list element contains the vector of H3 cells that cover the geometry.

## Usage

```
sfc_to_cells(x, resolution, containment = "intersect")
```

## Arguments

x	for <code>h3_from_points()</code> an object of class <code>sfc_POINT</code> . For <code>h3_from_strings()</code> a character vector of H3 index IDs. For <code>h3_from_xy()</code> a numeric vector of longitudes.
resolution	an integer indicating the H3 cell resolution. Must be between 0 and 15 inclusive.
containment	default "intersect". Must be one of "intersect", "centroid", or "boundary". See details.

## Details

Note, use `flatten_h3()` to reduce the list to a single vector.

The **Containment Mode** determines if an H3 cell should be returned.

- "centroid" returns every cell whose centroid are contained inside of a polygon. This is the fastest option but may not cover the entire polygon.
- "boundary" this returns the cells which are completely contained by the polygon. Much of a polygon might not be covered using this approach.
- "intersect" ensures that a polygon is entirely covered. If an H3 cell comes in contact with the polygon it will be returned. This is the default.

## Examples

```
if (interactive() && rlang::is_installed("sf")) {  
  nc <- sf::st_read(system.file("shape/nc.shp", package = "sf"), quiet = TRUE)  
  geo <- sf::st_geometry(nc)  
  cells <- sfc_to_cells(geo, 5)  
  
  head(cells)  
  
  plot(flatten_h3(cells))  
}
```

# Index

as.character.H3 (h3\_from\_xy), 6  
as.character.H3Edge (h3\_edges), 5  
compact\_cells, 2  
flatten\_edges (h3\_edges), 5  
flatten\_h3 (h3\_from\_xy), 6  
get\_children (get\_parents), 2  
get\_children\_at (get\_parents), 2  
get\_children\_center (get\_parents), 2  
get\_children\_count (get\_parents), 2  
get\_children\_position (get\_parents), 2  
get\_face\_count (h3\_resolution), 8  
get\_parents, 2  
grid\_disk, 3  
grid\_distance (grid\_disk), 3  
grid\_distances (grid\_disk), 3  
grid\_local\_ij (grid\_disk), 3  
grid\_path\_cells (grid\_disk), 3  
grid\_path\_cells\_size (grid\_disk), 3  
grid\_ring (grid\_disk), 3  
h3\_base\_cell (h3\_resolution), 8  
h3\_edge\_cells (h3\_edges), 5  
h3\_edge\_destination (h3\_edges), 5  
h3\_edge\_origin (h3\_edges), 5  
h3\_edges, 5  
h3\_edges\_from\_strings (h3\_edges), 5  
h3\_from\_points (h3\_from\_xy), 6  
h3\_from\_strings (h3\_from\_xy), 6  
h3\_from\_xy, 6  
h3\_resolution, 8  
h3\_shared\_edge\_pairwise (h3\_edges), 5  
h3\_shared\_edge\_sparse (h3\_edges), 5  
h3\_to\_points (h3\_from\_xy), 6  
h3\_to\_vertexes (h3\_from\_xy), 6  
is\_edge (h3\_edges), 5  
is\_h3 (h3\_from\_xy), 6  
is\_nb\_pairwise, 9  
is\_nb\_sparse (is\_nb\_pairwise), 9  
is\_res\_class\_iii (h3\_resolution), 8  
is\_valid\_edge (h3\_edges), 5  
is\_valid\_h3 (h3\_resolution), 8  
sfc\_to\_cells, 9  
uncompact\_cells (compact\_cells), 2